

#### CSCI-UA.0480-003 Parallel Computing

#### Lecture 8: MPI - II

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Many slides of this lecture are adopted and slightly modified from: • Gerassimos Barlas

• Peter S. Pacheco



# Dealing with I/O

```
#include <stdio.h>
#include <mpi.h>
```

In all MPI implementations, all processes in MPI\_COMM\_WORLD have access to stdout and sterr.

```
int main(void) {
    int my rank, comm sz;
```

```
MPI_Init(NULL, NULL);
MPI_Comm_size(MPI_COMM_WORLD, &comm_sz);
MPI_Comm_rank(MPI_COMM_WORLD, &my_rank);
```

```
MPI_Finalize();
return 0;
/* main */
```

BUT .. In most of them there is no scheduling of access to output devices!

### Running with 6 processes

Proc	0	of	6	>	Does	anyone	have	а	toothpick?
Proc	1	of	6	>	Does	anyone	have	a	toothpick?
Proc	2	of	6	>	Does	anyone	have	а	toothpick?
Proc	4	of	6	>	Does	anyone	have	а	toothpick?
Proc	3	of	6	>	Does	anyone	have	а	toothpick?
Proc	5	of	6	>	Does	anyone	have	а	toothpick?

#### unpredictable output!!

Processes are competing for stdout
Result: nondeterminism!

# How About Input?

- Most MPI implementations only allow process 0 in MPI\_COMM\_WORLD to access to stdin.
- If there is some input needed:

   Process 0 must read the data and send to the other processes.

#### Function for reading user input

```
void Get_input(
              my rank /* in */.
     int
           comm_sz /* in */,
     int
     double* a_p /* out */,
     double* b_p /* out */,
     int * np /* out */) {
  int dest:
  if (my rank == 0) {
     printf("Enter a, b, and n\n");
     scanf("%lf %lf %d", a p, b p, n p);
     for (dest = 1; dest < comm sz; dest++) {
        MPI_Send(a_p, 1, MPI_DOUBLE, dest, 0, MPI_COMM_WORLD);
        MPI Send(b p, 1, MPI DOUBLE, dest, 0, MPI COMM WORLD);
        MPI_Send(n_p, 1, MPI_INT, dest, 0, MPI_COMM_WORLD);
     ł
  else \{ /* my_rank != 0 */
     MPI_Recv(ap, 1, MPI_DOUBLE, 0, 0, MPI_COMM_WORLD,
           MPI STATUS IGNORE);
     MPI_Recv(b_p, 1, MPI_DOUBLE, 0, 0, MPI_COMM_WORLD,
           MPI STATUS_IGNORE);
     MPI Recv(n p, 1, MPI INT, 0, 0, MPI COMM WORLD,
           MPI STATUS IGNORE);
  /* Get_input */
```

Let's apply what we've learned so far, to solve an example more sophisticated than printing strings!

## The Trapezoidal Rule





## The Trapezoidal Rule

Area of one trapezoid  $= \frac{h}{2}[f(x_i) + f(x_{i+1})]$ 

$$h = \frac{b-a}{n}$$

 $x_0 = a, x_1 = a + h, x_2 = a + 2h, \dots, x_{n-1} = a + (n-1)h, x_n = b$ 

Sum of trapezoid areas  $= h[f(x_0)/2 + f(x_1) + f(x_2) + \dots + f(x_{n-1}) + f(x_n)/2]$ 

#### Pseudo-code for a serial program

/\* Input: a, b, n \*/
h = (b-a)/n;
approx = (f(a) + f(b))/2.0;
for (i =1 ; i <= n-1; i++) {
 x\_i = a + i\*h;
 approx += f(x\_i);
}
approx = h\*approx;</pre>

#### Parallelizing the Trapezoidal Rule

- Partition problem solution into tasks ...
   As many tasks as possible.
- 2. Identify communication channels between tasks.
- 3. Aggregate tasks into composite tasks.
- 4. Map composite tasks to cores.

#### Tasks and communications for Trapezoidal Rule



# Parallel pseudo-code

```
1
      Get a. b. n;
 2
      h = (b-a)/n;
 3
      local n = n/comm sz;
      local_a = a + my_rank*local_n*h;
4
 5
      local b = local a + local n*h;
6
      local integral = Trap(local_a, local_b, local_n, h);
7
      if (my_rank != 0)
8
          Send local_integral to process 0;
9
      else /* my_rank == 0 */
10
         total integral = local integral;
11
         for (proc = 1; proc < comm_sz; proc++) {</pre>
12
             Receive local integral from proc;
13
             total integral += local integral;
14
15
       if (my rank == 0)
16
17
         print result:
```

## First version (1)

```
1
   int main(void) {
      int my_rank, comm_sz, n = 1024, local_n;
2
3
      double a = 0.0, b = 3.0, h, local a, local b;
4
      double local int, total int;
5
      int source:
6
7
      MPI Init(NULL, NULL);
8
      MPI Comm rank(MPI COMM WORLD, &my rank);
9
      MPI Comm size(MPI COMM WORLD, &comm sz);
10
      h = (b-a)/n; /* h is the same for all processes */
11
12
      local n = n/comm sz; /* So is the number of trapezoids */
13
14
      local a = a + my rank*local n*h;
15
      local b = local a + local n*h;
16
      local int = Trap(local a, local b, local n, h);
17
18
      if (my rank != 0) {
         MPI_Send(&local_int, 1, MPI_DOUBLE, 0, 0.
19
20
               MPI COMM WORLD);
```

# First version (2)

```
21
      } else {
22
         total int = local int;
23
         for (source = 1; source < comm sz; source++) {</pre>
24
            MPI Recv(&local int, 1, MPI DOUBLE, source, 0,
25
                   MPI COMM WORLD, MPI STATUS IGNORE);
26
            total int += local int;
27
28
29
30
      if (my rank == 0) {
31
         printf("With n = %d trapezoids, our estimate\n", n);
32
         printf("of the integral from %f to %f = %.15e\n",
33
              a. b. total int):
34
35
      MPI Finalize();
36
      return 0;
37
        main */
     1*
```

# First version (3)

```
double Trap(
 1
2
         double left_endpt /* in */,
3
         double right endpt /* in */,
4
         int trap count /* in */.
5
         double base_len /* in */) {
6
      double estimate, x;
7
      int i:
8
9
      estimate = (f(left endpt) + f(right endpt))/2.0;
10
      for (i = 1; i \le trap_count - 1; i++)
11
         x = left_endpt + i*base_len;
12
         estimate += f(x);
      }
13
14
      estimate = estimate*base_len;
15
16
      return estimate;
17
   } /* Trap */
```

### The Final Sum ... Tree again!



# An alternative tree-structured global sum



#### Reduction

- Reducing a set of numbers into a smaller set of numbers via a function
  - Example: reducing the group [1, 2, 3, 4, 5] with the sum function  $\rightarrow$  15
- MPI provides a handy function that handles almost all of the common reductions that a programmer needs to do in a parallel application

MPI\_Reduce



Every process has an element

MPI\_Reduce



Every process has an array of elements



Examples:

MPI\_Reduce is called by all processes involved.

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This is why it is called **collective call**.

#### Predefined reduction operators in MPI

<b>Operation Value</b>	Meaning
MPI_MAX	Maximum
MPI_MIN	Minimum
MPI_SUM	Sum
MPI_PROD	Product
MPI_LAND	Logical and
MPI_BAND	Bitwise and
MPI_LOR	Logical or
MPI_BOR	Bitwise or
MPI_LXOR	Logical exclusive or
MPI_BXOR	Bitwise exclusive or
MPI_MAXLOC	Maximum and location of maximum
MPI_MINLOC	Minimum and location of minimum

Location = rank of the process that owns it

#### Collective vs. Point-to-Point Communications

- <u>All</u> the processes in the communicator must call the same collective function.
  - For example, a program that attempts to match a call to MPI\_Reduce on one process with a call to MPI\_Recv on another process is erroneous.
- The arguments passed by each process to an MPI collective communication must be "compatible."
  - For example, if one process passes in 0 as the dest\_process and another passes in 1, then the outcome of a call to MPI\_Reduce is erroneous.

Collective vs. Point-to-Point Communications

- The output\_data\_p argument is only used on dest\_process.
- However, all of the processes still need to pass in an actual argument corresponding to output\_data\_p, even if it's just NULL.
- All collective communication calls are blocking.

Collective vs. Point-to-Point Communications

- Point-to-point communications are matched on the basis of tags and communicators.
- Collective communications don't use tags.
- They're matched solely on the basis of the communicator and the order in which they're called.

# Example

Time	Process 0	Process 1	Process 2		
0	a = 1; c = 2	a = 1; c = 2	a = 1; c = 2		
1	MPI_Reduce(&a, &b,)	MPI_Reduce(&c, &d,)	MPI_Reduce(&a, &b,)		
2	MPI_Reduce(&c, &d,)	MPI_Reduce(&a, &b,)	MPI_Reduce(&c, &d,)		

Assume:

- all processes use the operator MPI\_SUM
- destination is process 0

#### What will be the final values of b and d??

#### Yet Another Example

MPI\_Reduce(&x, &x, 1, MPI\_DOUBLE, MPI\_SUM, 0, comm);

This is illegal in MPI and the result is non-predictable!

#### MPI\_Allreduce

 Useful in a situation in which all of the processes need the result of a global sum in order to complete some larger computation.

```
int MPI_Allreduce(
         void *
                      input_data_p /* in
                                            */,
         void *
                      output_data_p /* out */,
        int
                                   /* in */,
                      count
                                    /* in */.
        MPI_Datatype datatype
                                     /* in */.
        MPI_Op
                      operator
                                            */);
        MPI_Comm
                                     /* in
                      COMM
```

No destination argument!

## Broadcast

 Data belonging to a single process is sent to all of the processes in the communicator.

int	MPI_Bcast(				
	void *	data_p	/*	in/out	*/,
	int	count	/*	i n	*/,
	MPI_Datatype	datatype	/*	in	*/,
	int	source_proc	/*	in	*/,
	MPI_Comm	comm	/*	in	*/);

ALL processes in the communicator must call MPI\_Bcast()



#### A version of Get\_input that uses MPI\_Bcast

```
void Get_input(
     int my rank /* in */,
     int comm_sz /* in */,
     double * a_p /* out */,
     double* b_p /* out */,
     int * n_p /* out */) {
  if (my_rank == 0) {
     printf("Enter a, b, and n\n");
     scanf("%lf %lf %d", a_p, b_p, n_p);
  MPI_Bcast(a_p, 1, MPI_DOUBLE, 0, MPI_COMM_WORLD);
  MPI Bcast(b p, 1, MPI DOUBLE, 0, MPI COMM WORLD);
  MPI_Bcast(n_p, 1, MPI_INT, 0, MPI_COMM_WORLD);
 /* Get_input */
```

#### Conclusions

- A communicator is a collection of processes that can send messages to each other.
- Collective communications involve all the processes in a communicator.
- When studying MPI be careful of the caveats (i.e. usage that leads to crash, nondeterministic behavior, ... ).